

**CSCI 2820** 

Lecture 11

Prof. Alexandra Kolla

Alexandra.Kolla@Colorado.edu ECES 122

# Today

- Coordinate systems
- Projections
- Gram-Schmidt re-explained

## Unique Representation

#### The Unique Representation Theorem

Let  $\mathcal{B} = \{\mathbf{b}_1, \dots, \mathbf{b}_n\}$  be a basis for a vector space V. Then for each  $\mathbf{x}$  in V, there exists a unique set of scalars  $c_1, \dots, c_n$  such that

$$\mathbf{x} = c_1 \mathbf{b}_1 + \dots + c_n \mathbf{b}_n \tag{1}$$

## Coordinate Systems

**DEFINITION** 

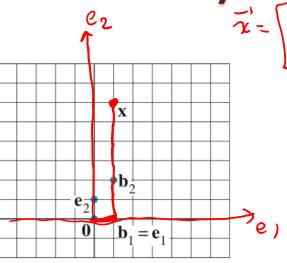
Suppose  $\mathcal{B} = \{\mathbf{b}_1, \dots, \mathbf{b}_n\}$  is a basis for V and  $\mathbf{x}$  is in V. The **coordinates of \mathbf{x}** relative to the basis  $\mathcal{B}$  (or the  $\mathcal{B}$ -coordinates of  $\mathbf{x}$ ) are the weights  $c_1, \dots, c_n$  such that  $\mathbf{x} = c_1 \mathbf{b}_1 + \dots + c_n \mathbf{b}_n$ .

eg! 
$$\vec{x} = \begin{bmatrix} 1 \\ 6 \end{bmatrix} = 1.\vec{e}_1 + 6.\vec{e}_2$$
 "standard basis"

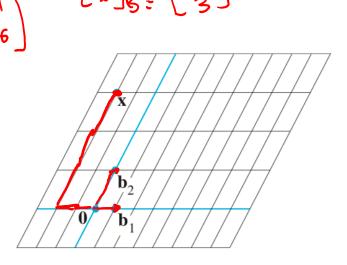
eg!  $\vec{x} = \begin{bmatrix} 1 \\ 6 \end{bmatrix} = 1.\vec{e}_1 + 6.\vec{e}_2$  "standard basis"

$$\vec{x} = \begin{bmatrix} 1 \\ 6 \end{bmatrix} = \begin{bmatrix} 1 \\ 6 \end{bmatrix}$$

Coordinate Systems



**FIGURE 1** Standard graph paper.



**FIGURE 2**  $\mathcal{B}$ -graph paper.

If a vector space V has a basis  $\mathcal{B} = \{\mathbf{b}_1, \dots, \mathbf{b}_n\}$ , then any set in V containing more than n vectors must be linearly dependent.

If a vector space V has a basis of n vectors, then every basis of V must consist of exactly n vectors.

If V is spanned by a finite set, then V is said to be **finite-dimensional**, and the **dimension** of V, written as  $\dim V$ , is the number of vectors in a basis for V. The dimension of the zero vector space  $\{0\}$  is defined to be zero. If V is not spanned by a finite set, then V is said to be **infinite-dimensional**.

Let H be a subspace of a finite-dimensional vector space V. Any linearly independent set in H can be expanded, if necessary, to a basis for H. Also, H is finite-dimensional and

 $\dim H \leq \dim V$ 

#### The Basis Theorem

Let V be a p-dimensional vector space,  $p \ge 1$ . Any linearly independent set of exactly p elements in V is automatically a basis for V. Any set of exactly p elements that spans V is automatically a basis for V.

Find the dimension of the subspace H of  $\mathbb{R}^2$  spanned by

$$\begin{bmatrix} 2 \\ -5 \end{bmatrix}, \begin{bmatrix} -4 \\ 10 \end{bmatrix}, \begin{bmatrix} -3 \\ 6 \end{bmatrix}$$

$$\overrightarrow{x}_{1} = -2 \cdot \overrightarrow{x}_{1}$$

$$\begin{bmatrix} 2 \\ -5 \end{bmatrix}, \begin{bmatrix} -4 \\ 10 \end{bmatrix}, \begin{bmatrix} -3 \\ 6 \end{bmatrix}.$$

$$\begin{cases} x_1, x_3 \\ x_2 \end{cases} \text{ busis for } 1 \\ \text{einearly indep} \end{cases}$$

$$\begin{cases} x_1 \\ x_2 \\ x_3 \end{cases} = -2 \cdot x_1$$

$$\begin{cases} x_1 \\ x_2 \\ x_3 \end{cases}$$

$$\begin{cases} x_1 \\ x_3 \\ x_4 \end{cases} = -2 \cdot x_1$$

#### True or False?

- a. If there exists a set  $\{\mathbf{v}_1, \dots, \mathbf{v}_p\}$  that spans V, then
- b. If there exists a linearly independent set  $\{\mathbf{v}_1,\ldots,\mathbf{v}_p\}$  in V, then  $\dim V \geq p$ . Then there exists the exists V is the set of V and V is the exists V in V in
- c. If dim V = p, then there exists a spanning set of p + 1vectors in V.7  $V=1/2^3$  span  $\{\vec{e}_1,\vec{e}_2,\vec{e}_3,\vec{e}_1+5\vec{e}_2+3\vec{e}_3\}=1/2^3$   $\dim(V)=3$  span  $\{\vec{e}_1,\vec{e}_2,\vec{e}_3,\vec{e}_1+5\vec{e}_2+3\vec{e}_3\}=1/2^3$ vectors in V. 7

ic dim v= P+2 then "c" would be F

#### True or False?

- a. If there exists a linearly dependent set  $\{v_1, \dots, v_p\}$  in V, then dim  $V \le p$ .  $V = \mathbb{R}^3 \setminus \{\vec{e_1}, \vec{z_0}, \vec{f_2}\} = 2$  but dim V = 3
- b. If every set of p elements in V fails to span V, then  $\dim V > p$ .
- $\neq$  c. If  $p \ge 2$  and dim V = p, then every set of p 1 nonzero vectors is linearly independent.

